

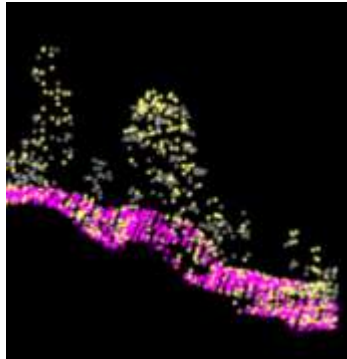
# SMART Forest

**The digital forest: opportunities for innovation and improved forest management**

Rasmus Astrup, NIBIO

# Background Norway: State of forest information

National LIDAR  
campaign



NFI  
3 by 3 km systematic grid

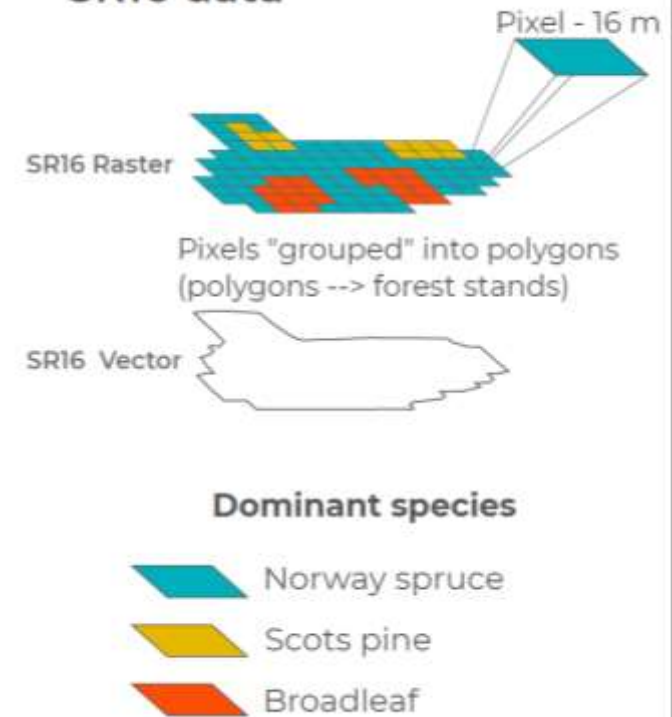


$$y = f(\beta, X, \gamma) + \epsilon$$



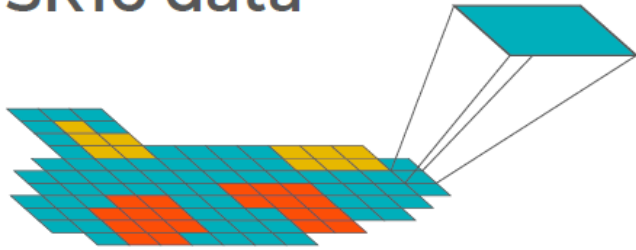
National free forest  
resource map SR16

SR16 data



# Pixel-level information we are using:

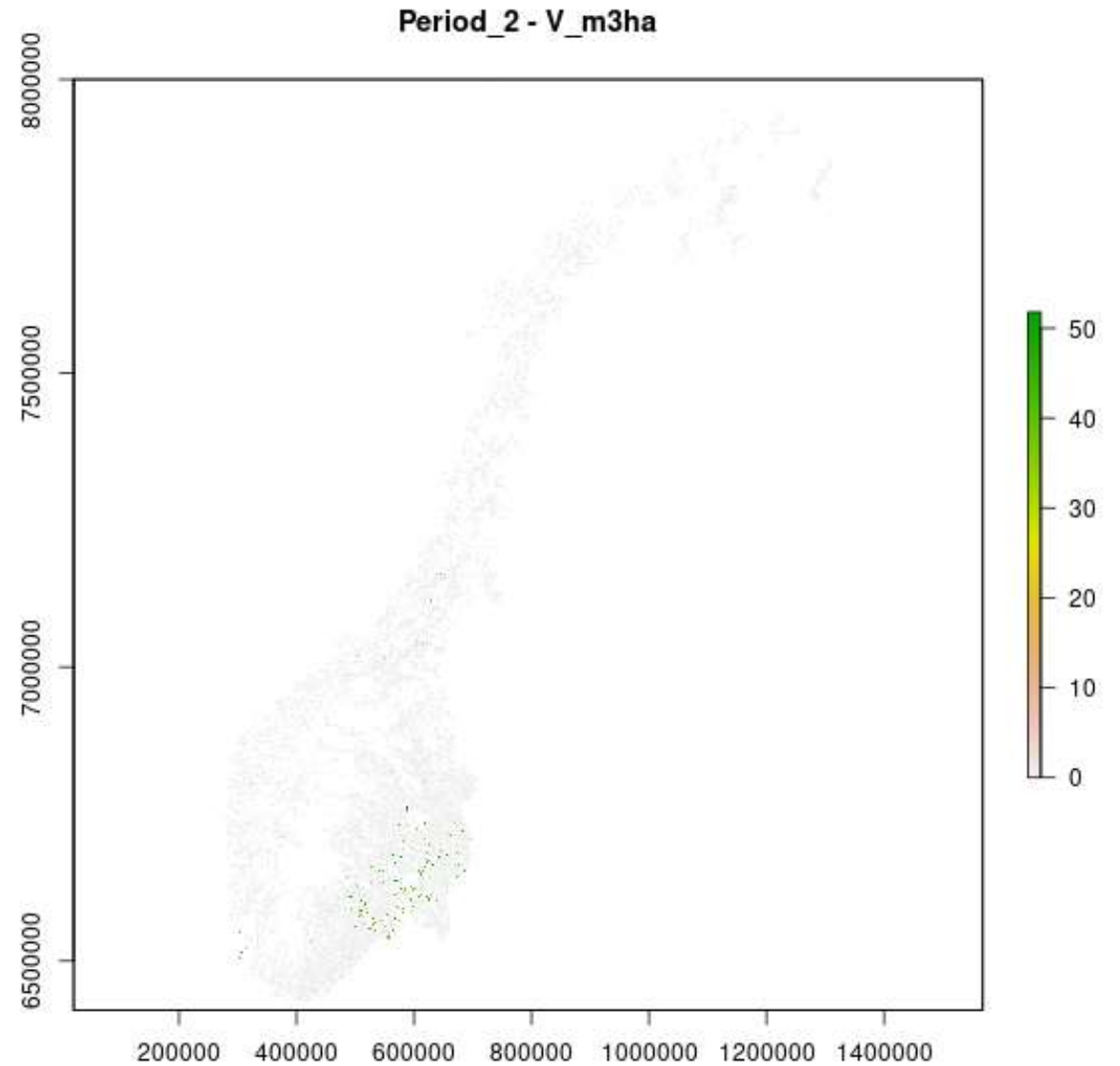
## SR16 data

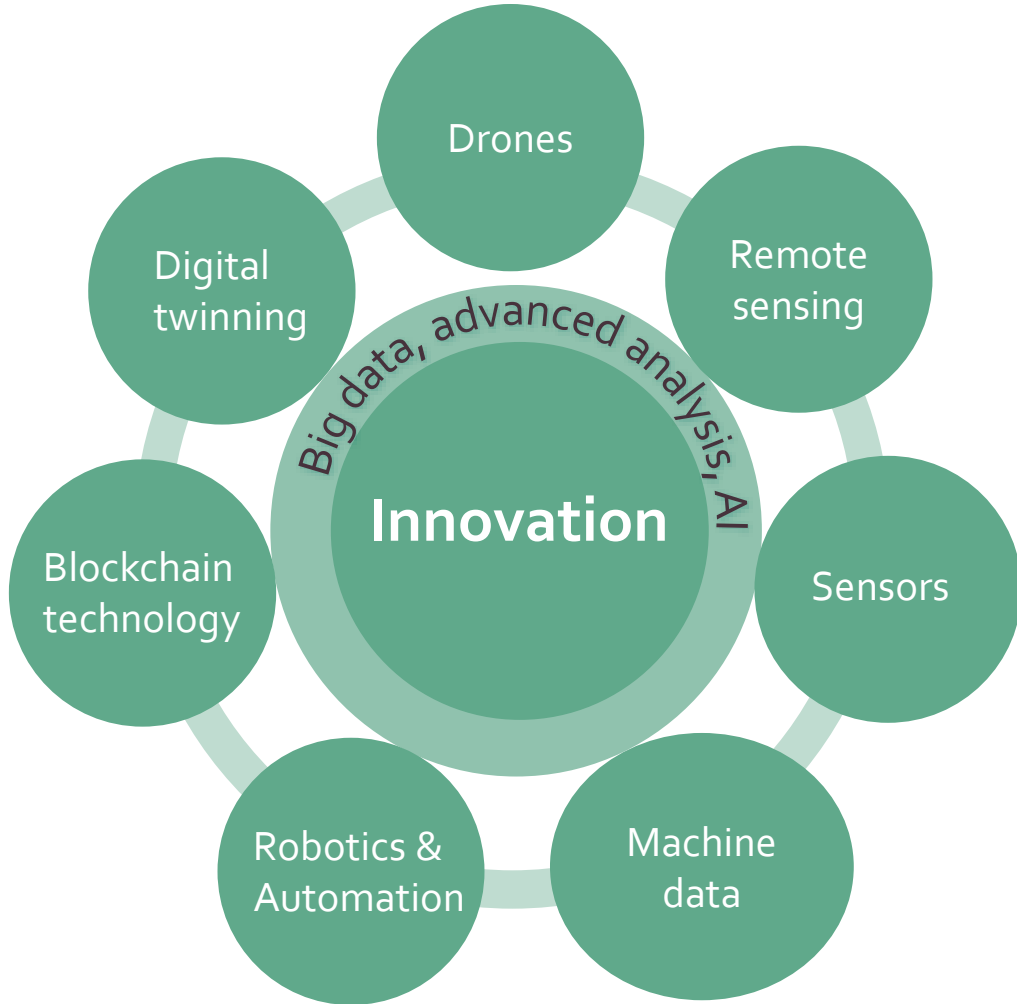


- Site index (m, age 40)
- Number of trees per ha
- Basal area (m<sup>2</sup>/ha)
- Dominant height (m)
- Stand volume (m<sup>3</sup>/ha)

## Extra info

- Distance to the nearest road
- Pixel inside MiS (Miljøregistrering i skog)
- Elevation, slope
- ...





How can we use emerging technologies to improve sustainable forest management?







Forest inventory

Silviculture

Harvesting

Wood supply







Healthy



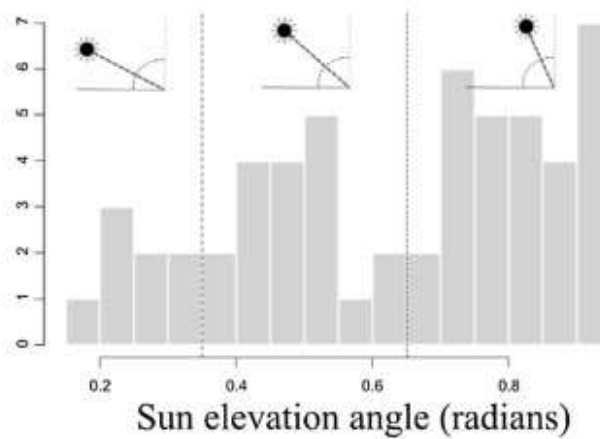
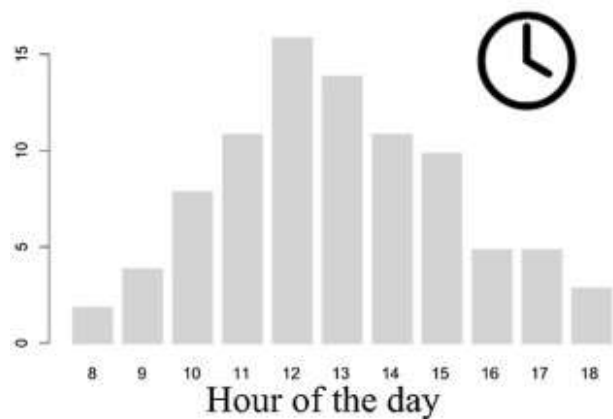
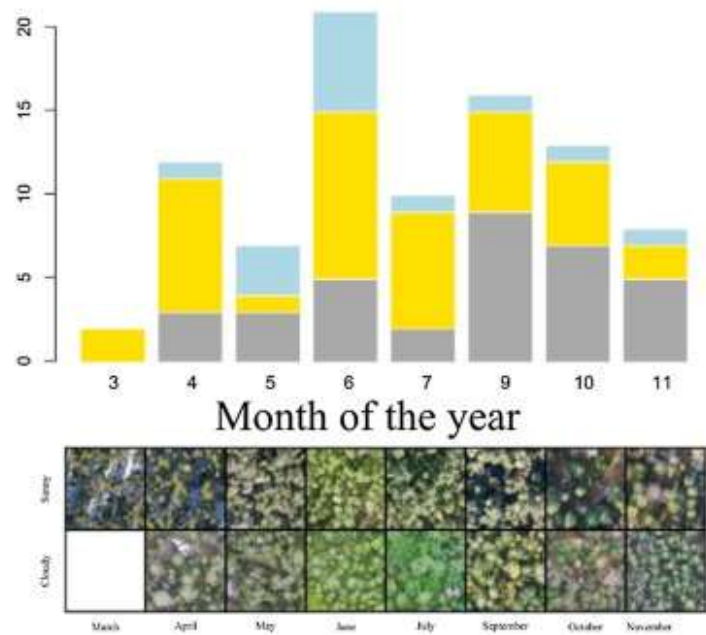
Broken-top



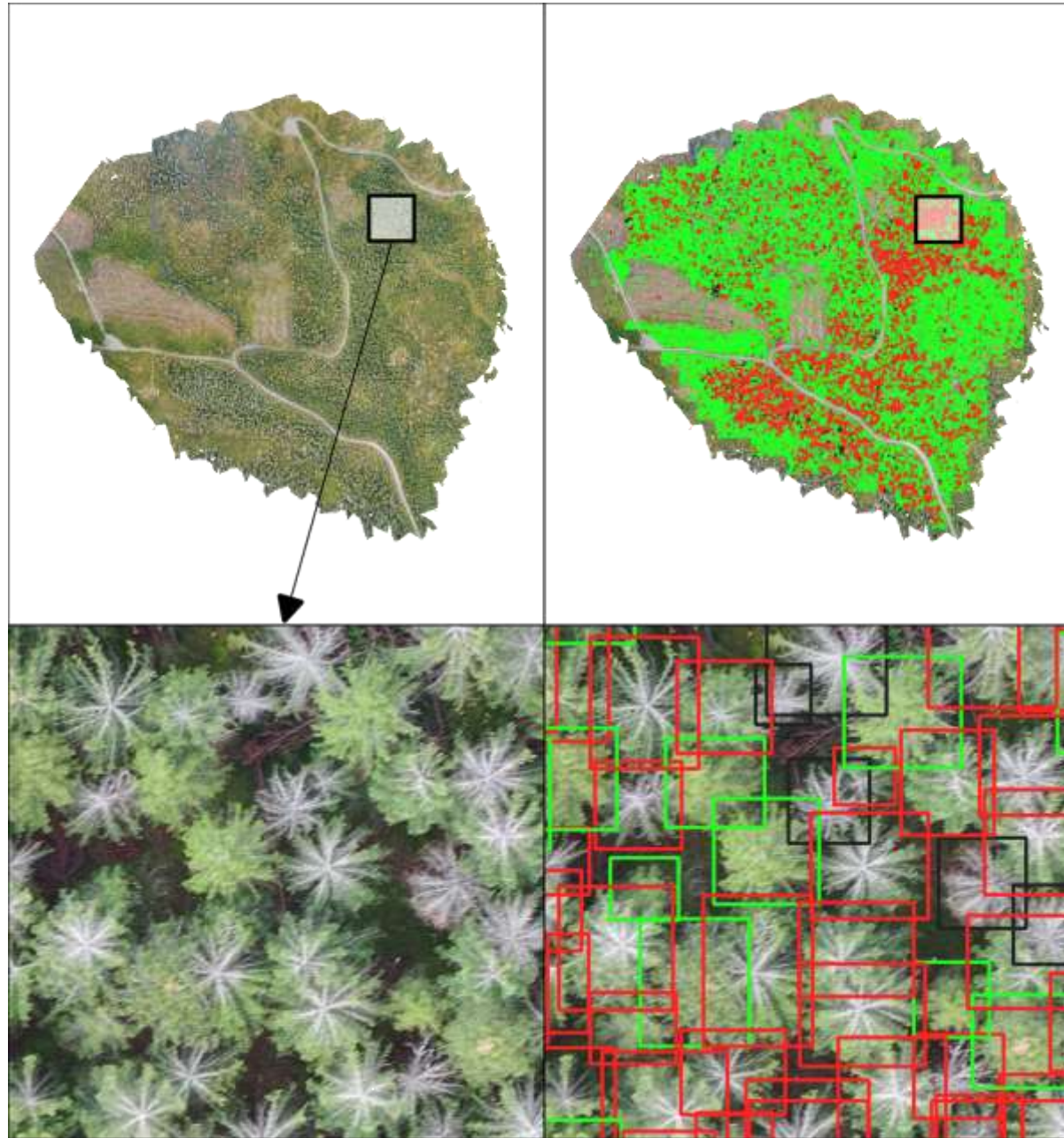
Dead







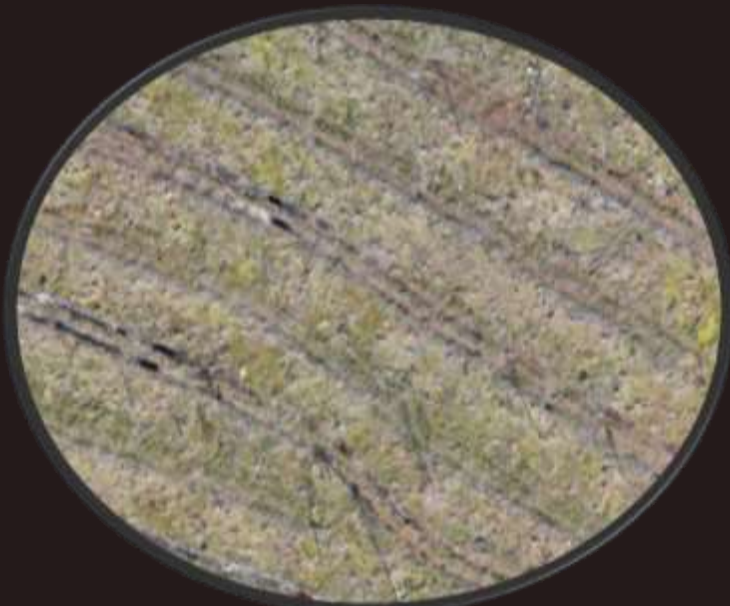
The training set was composed of 65 UAV acquisitions, 479 tiles, 40 697 trees, out of which 16 % were damaged by snow.



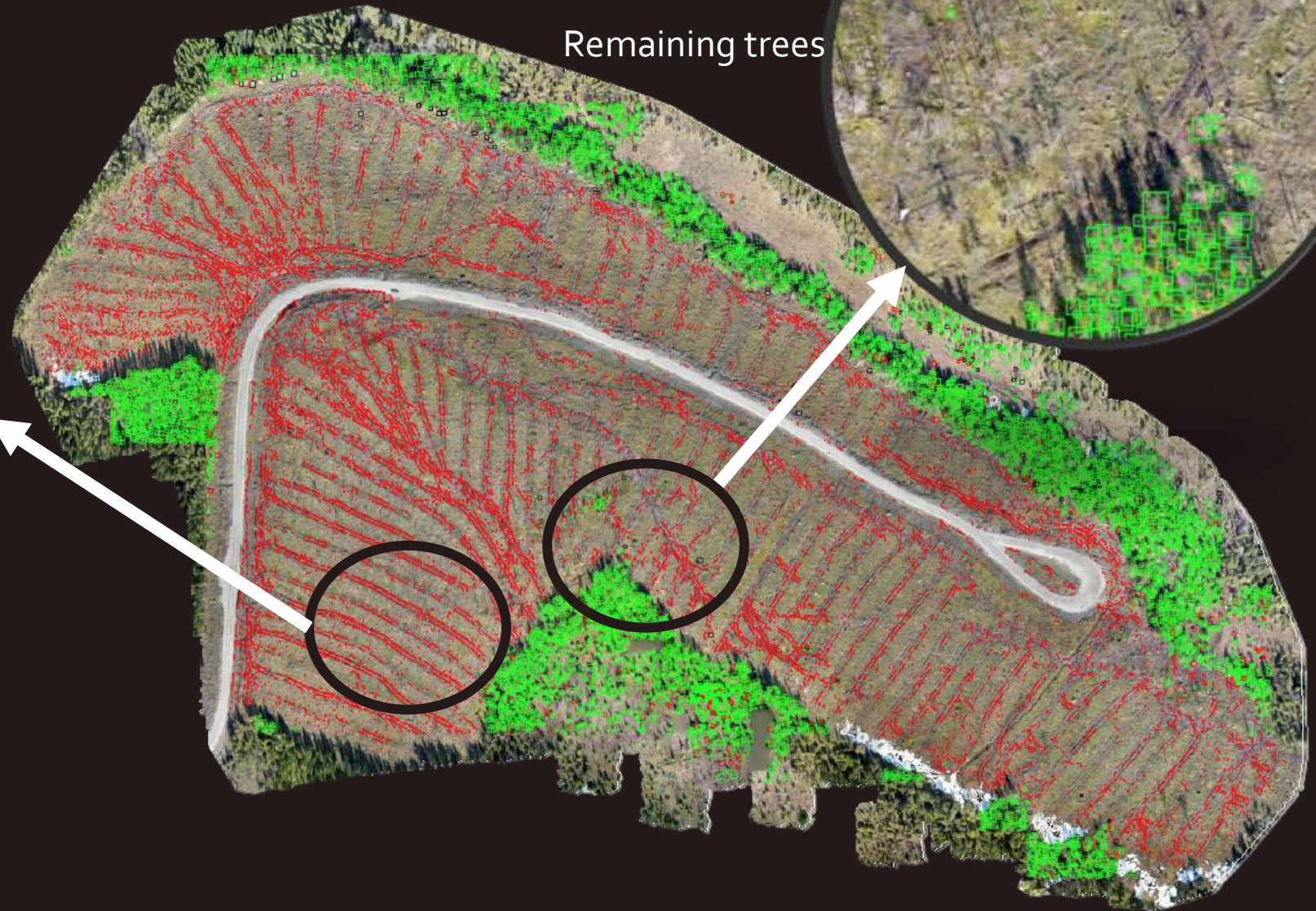
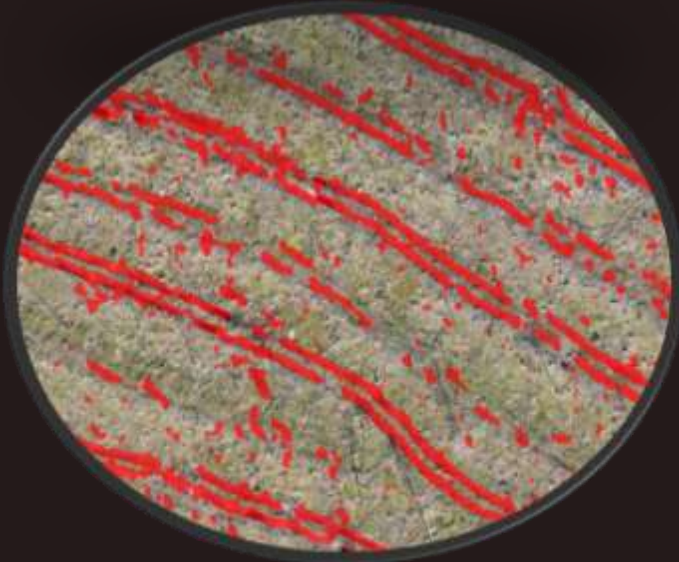
Puliti and Astrup (2022).



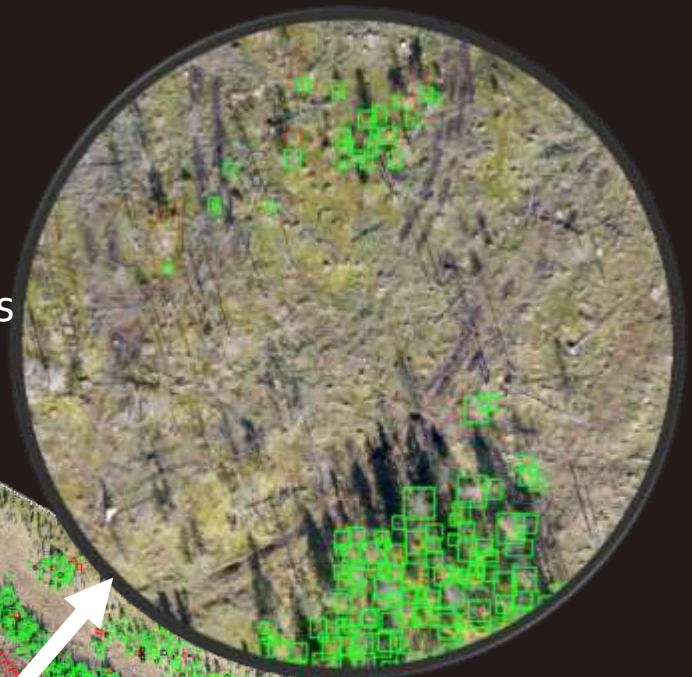
# Post Harvest assessment



Wheel-ruts

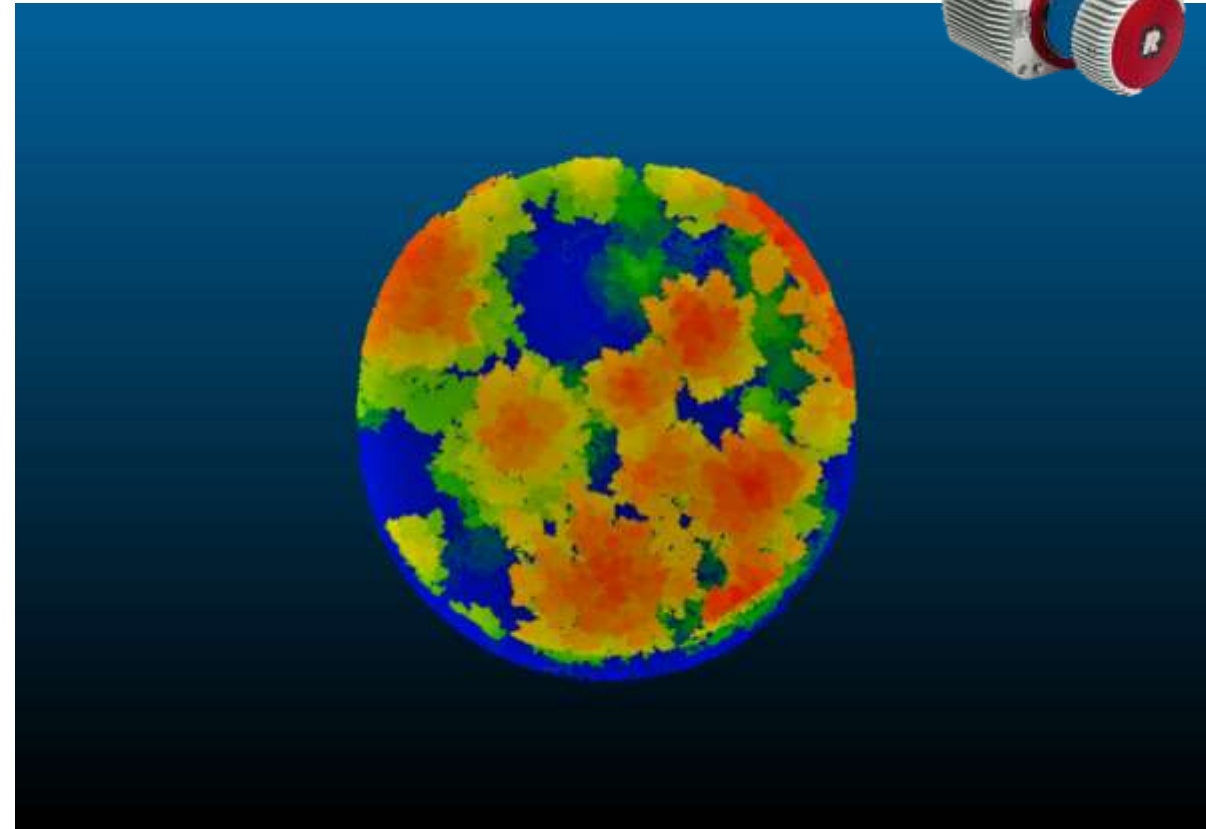
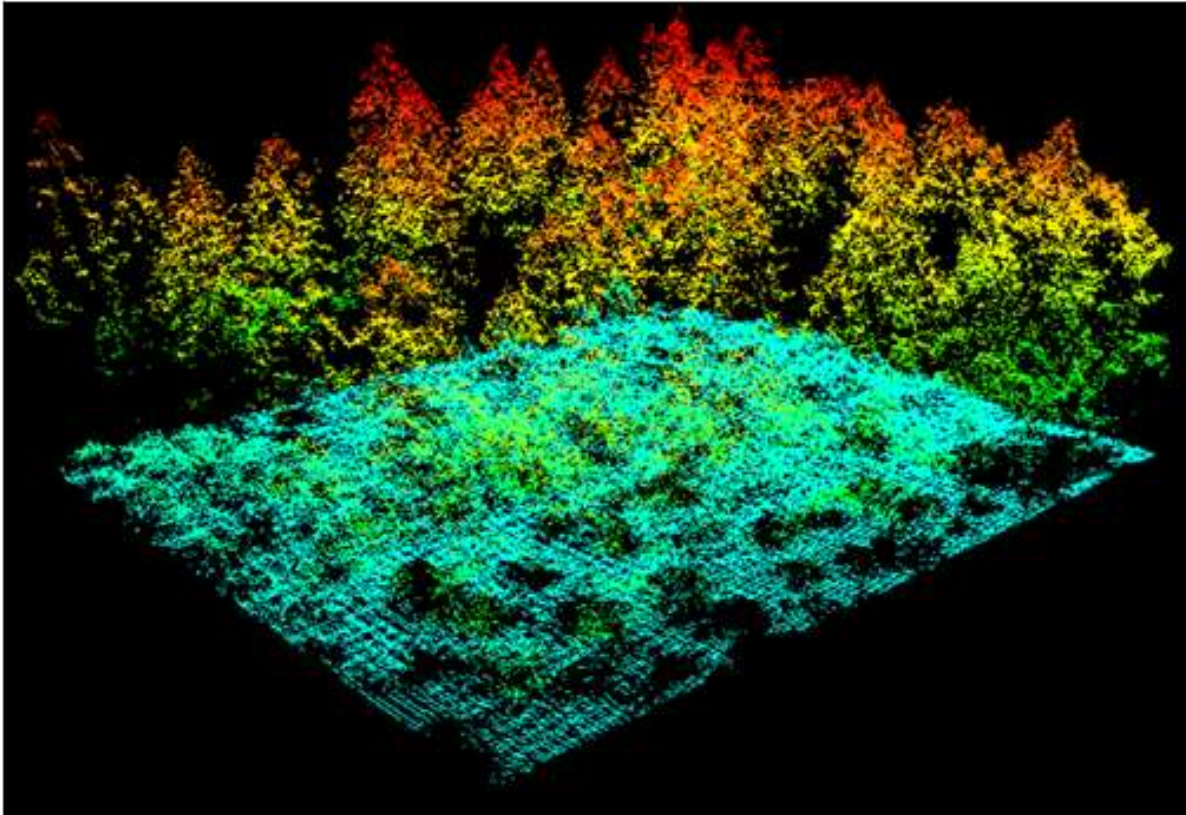


Remaining trees





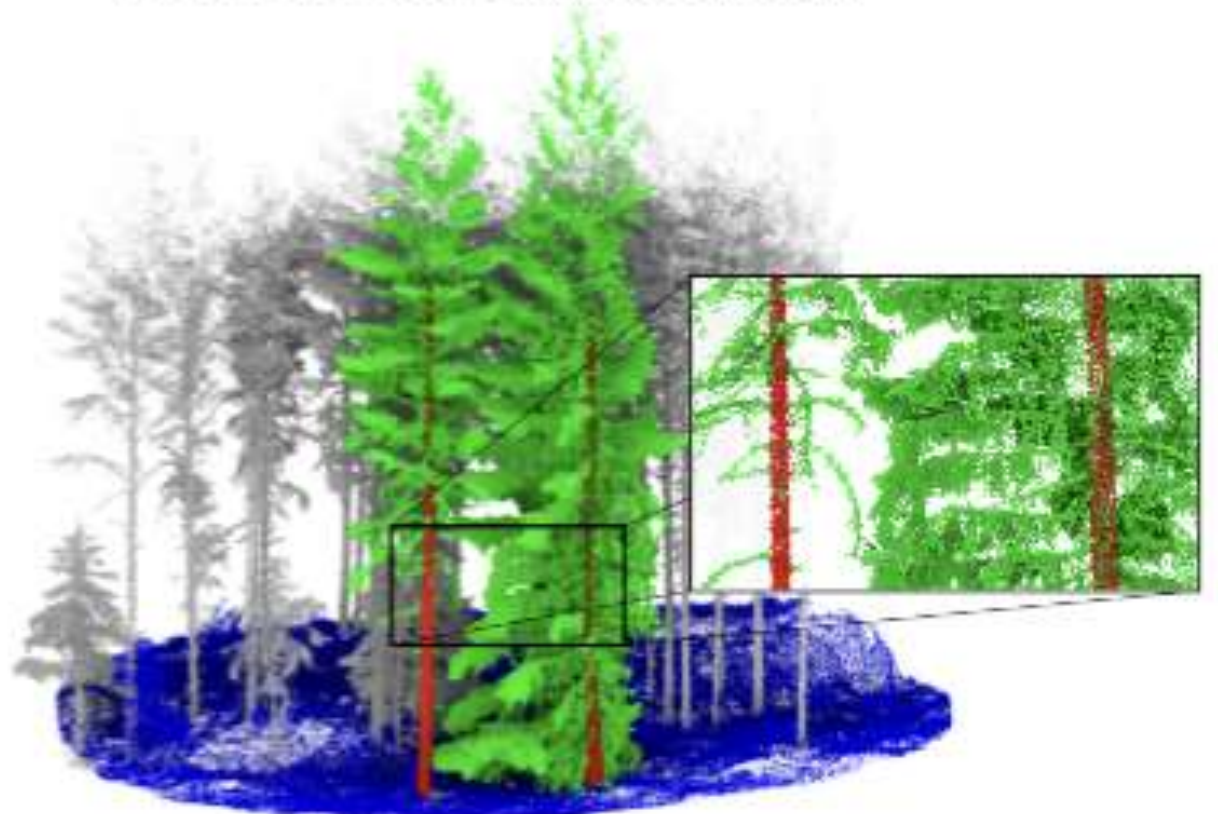
## 3D data: from operational low density point clouds to ultra high resolution



# Instance annotation



# Semantic annotation

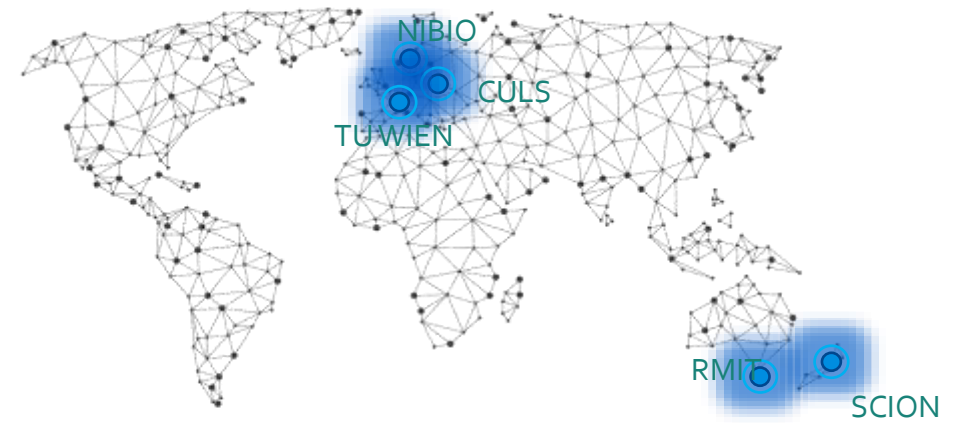






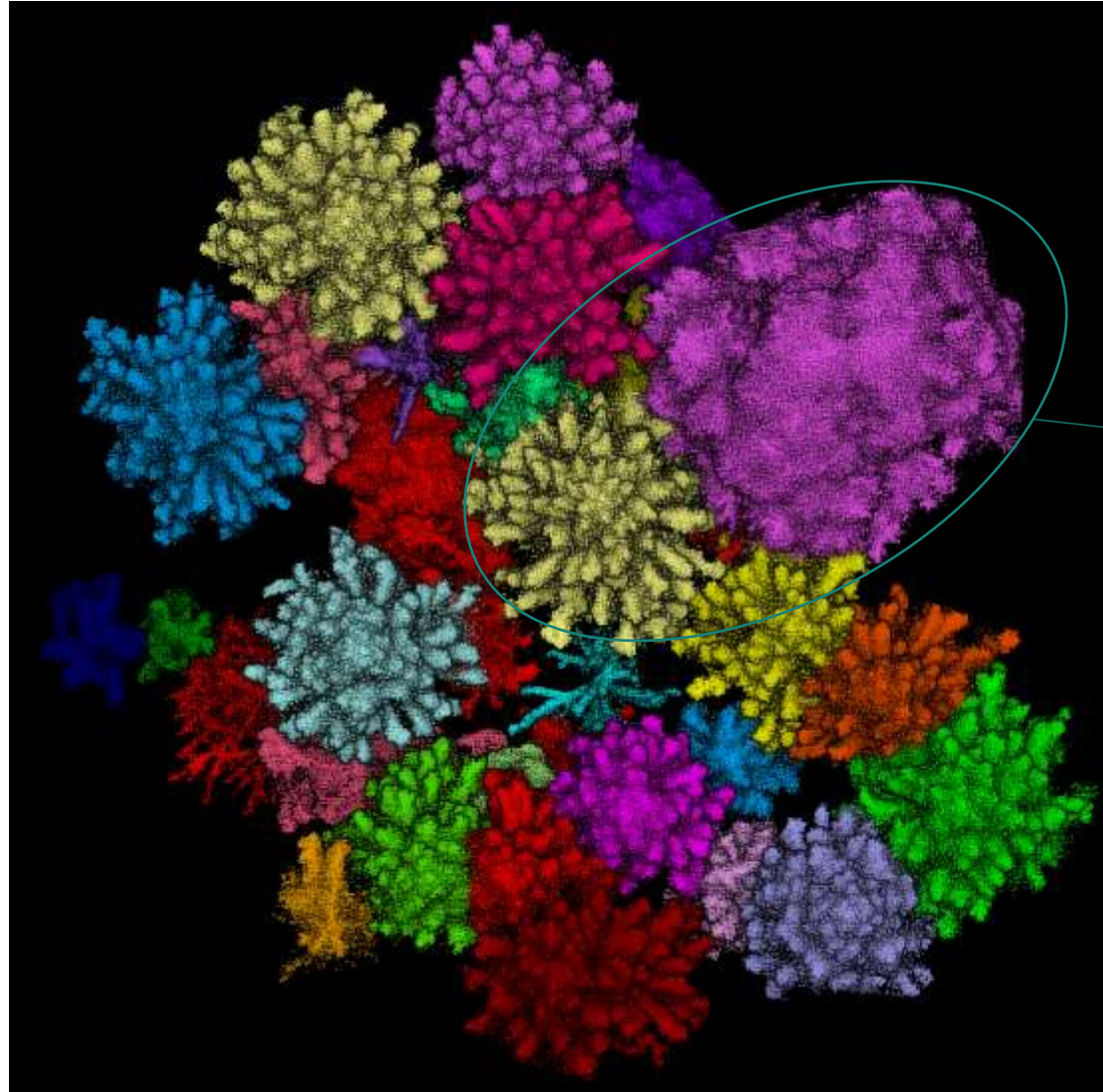
## A UAV lidar benchmark dataset for forest instance segmentation and measurement biophysical properties

Puliti, S., Pearse, G.D., Watt, M.S., Mitchard, E., McNicol, I., Bremer, M., Rutzinger, M., Surovy, P., Wallace, L., Hollaus, M., and Astrup, R.

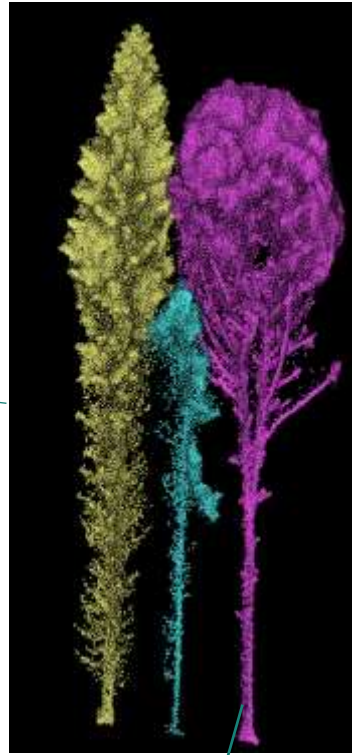




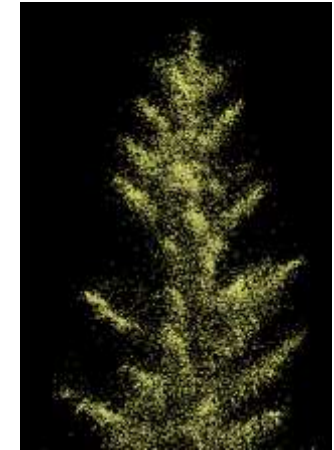
# Manual annotation



Single trees



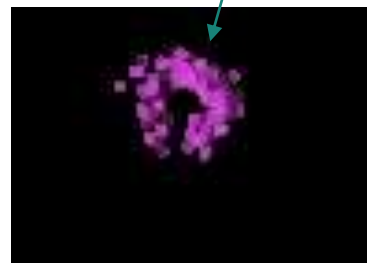
Stem  
Live and dead  
Branches



Vertical slice  
spruce  
tree-top

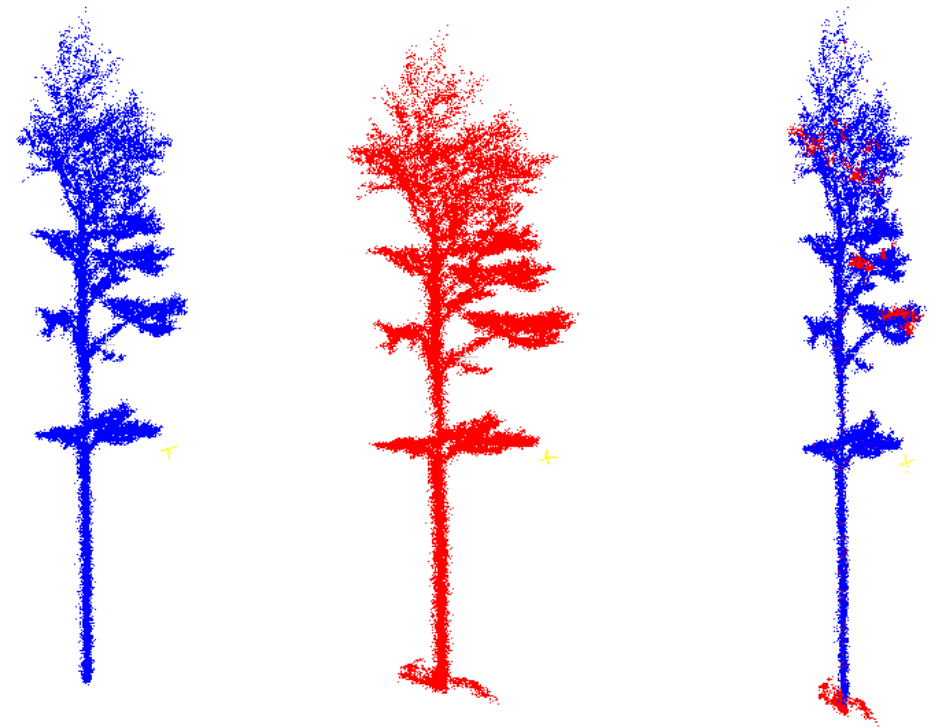
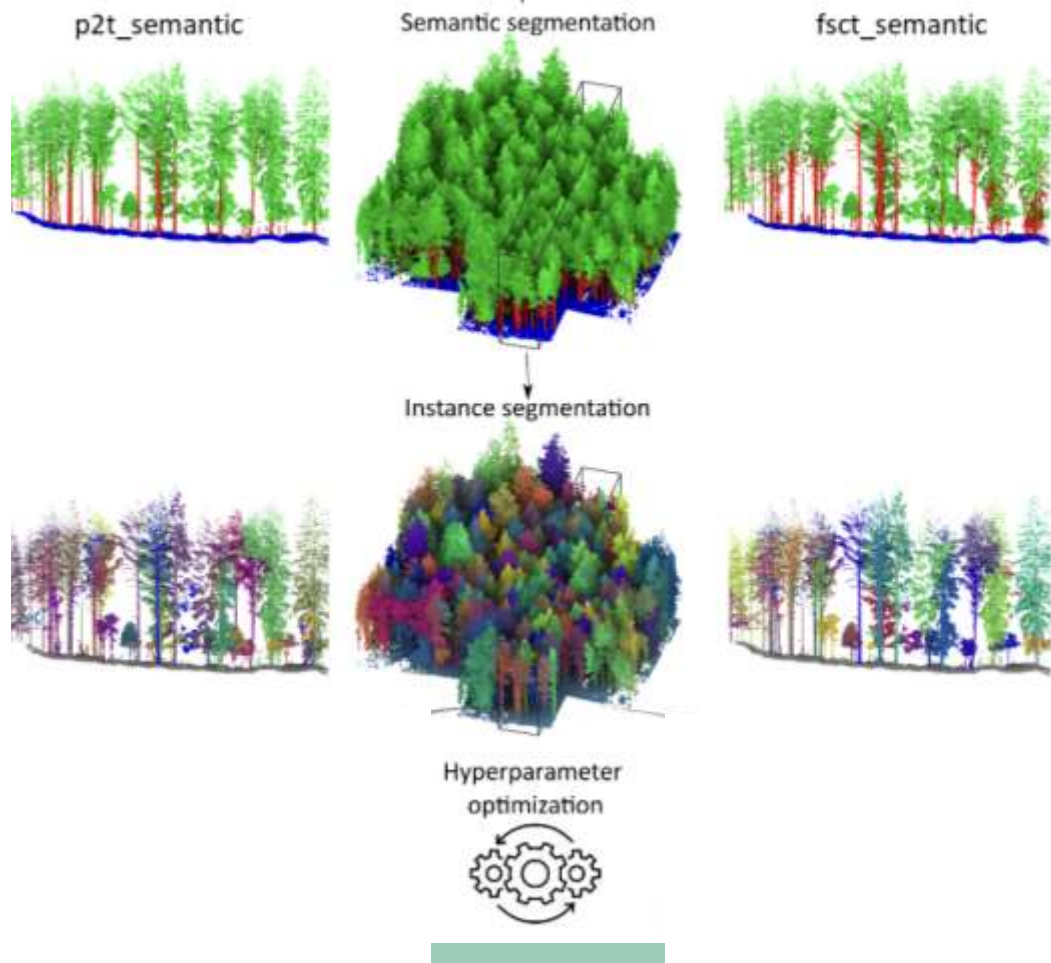


Vertical slice  
spruce dead  
crown



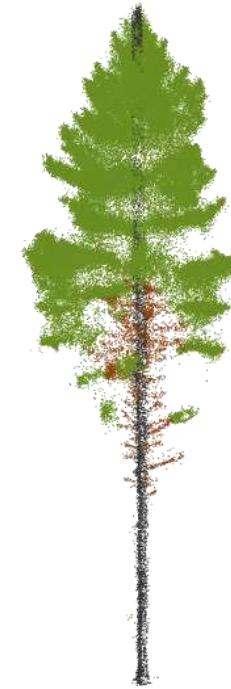
Horizontal slice at DBH

# Point2Tree (P2T) - framework for parameter tuning of semantic and instance segmentation

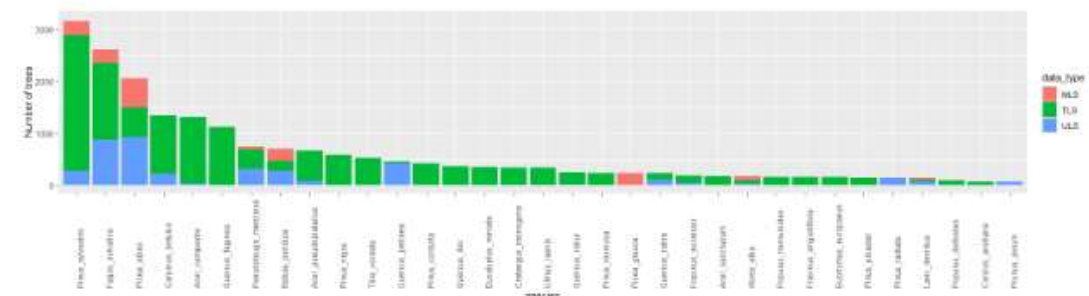


Manual (red) and Predicted (blue) for precision=0.99, recall=0.90, f1=0.94, IoU=0.89 on LAUTx (Tockner et al. 2022)

# Benchmarking dataset for sensor-agnostic tree species classification using proximal laser scanning (TLS, MLS, ULS) - 20 000 individual point clouds



Tree distribution by tree species (33 tree species with more than 50 trees)





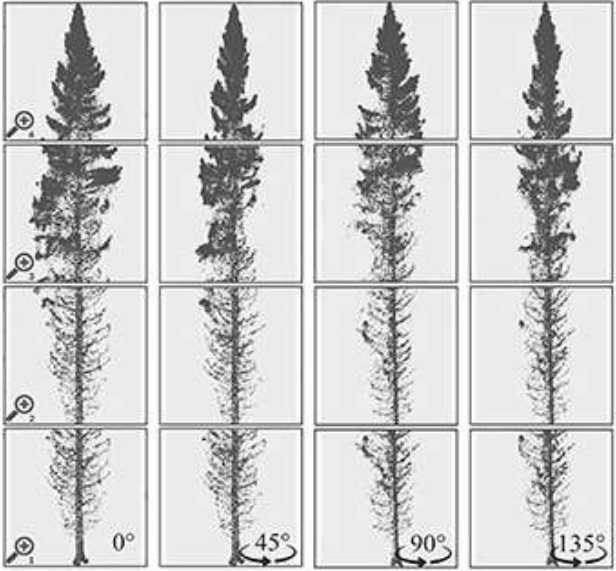
# 2D image analysis for 3D point clouds

## ii) Generation of images of the single trees

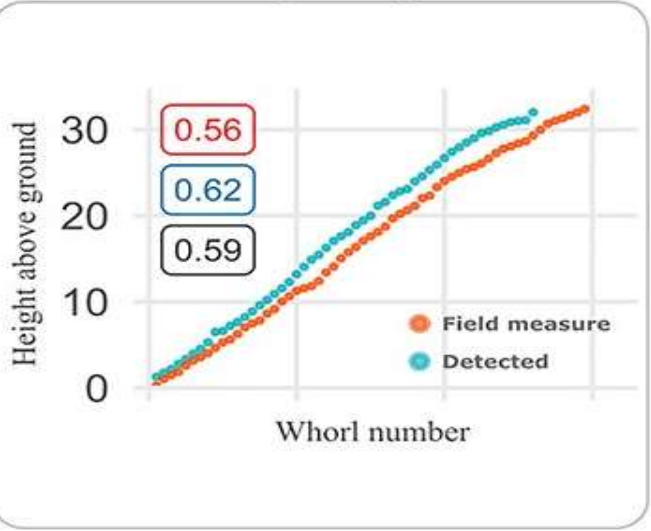
Radial slices of the tree in cardinal directions



2D projection of radial slices



Yolo whorl detector



Forest inventory

Silviculture

Harvesting

Wood supply

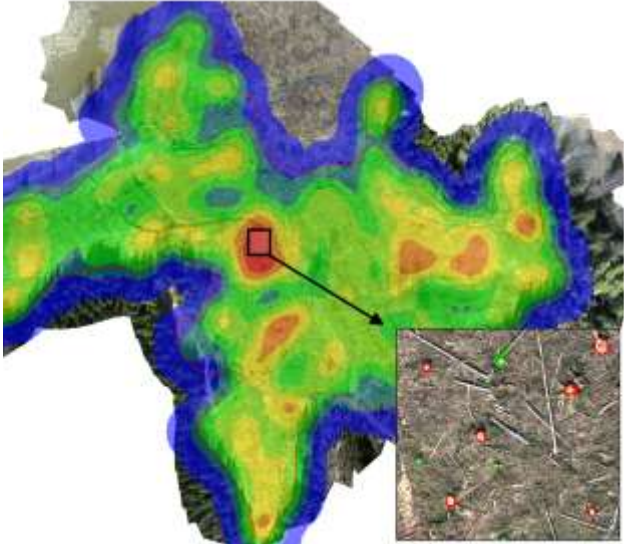
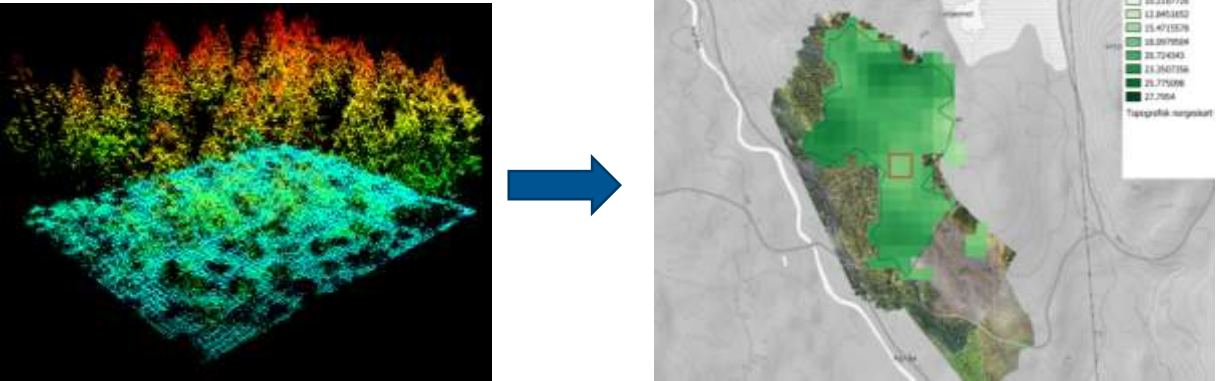




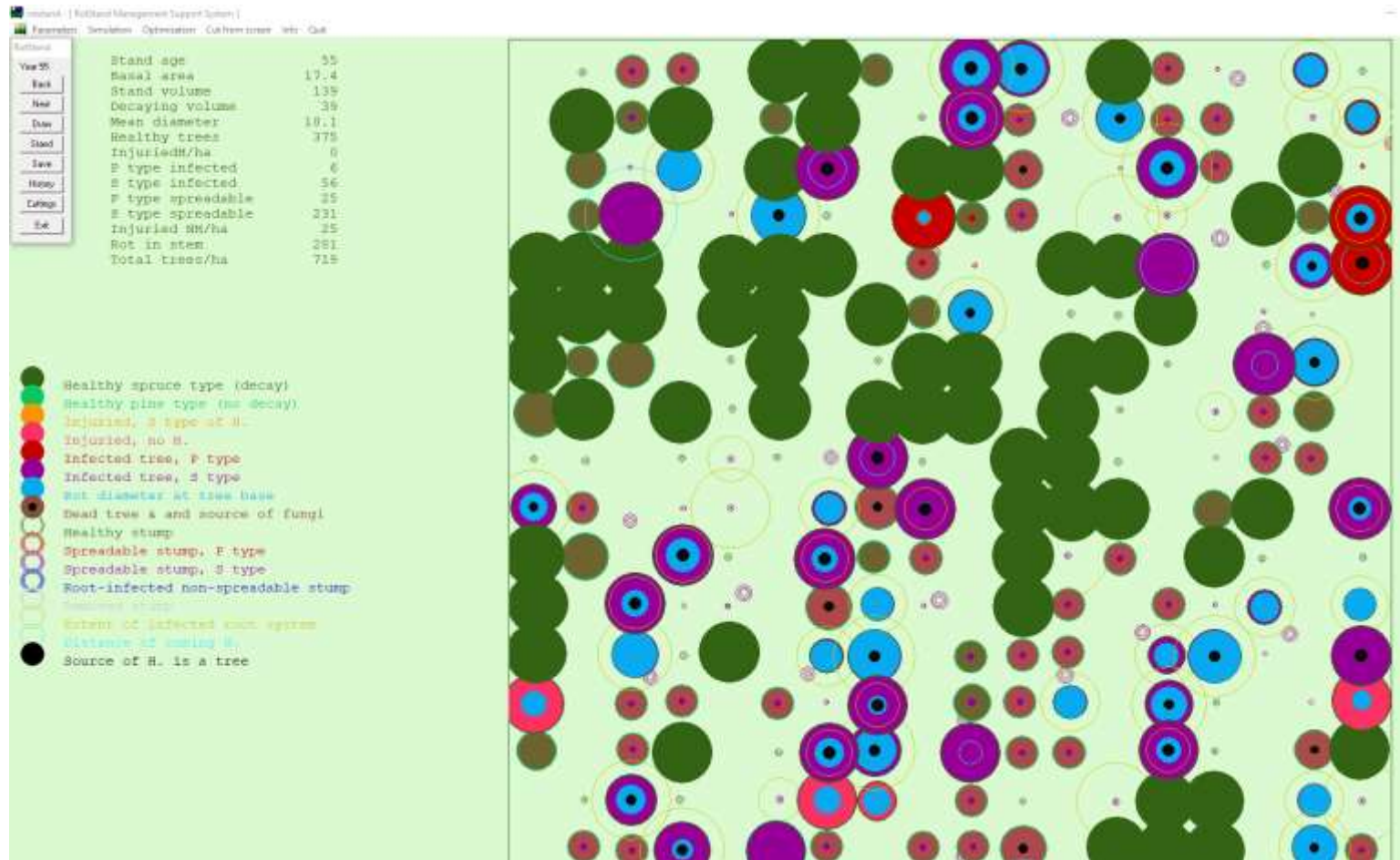
# Precision silviculture



?

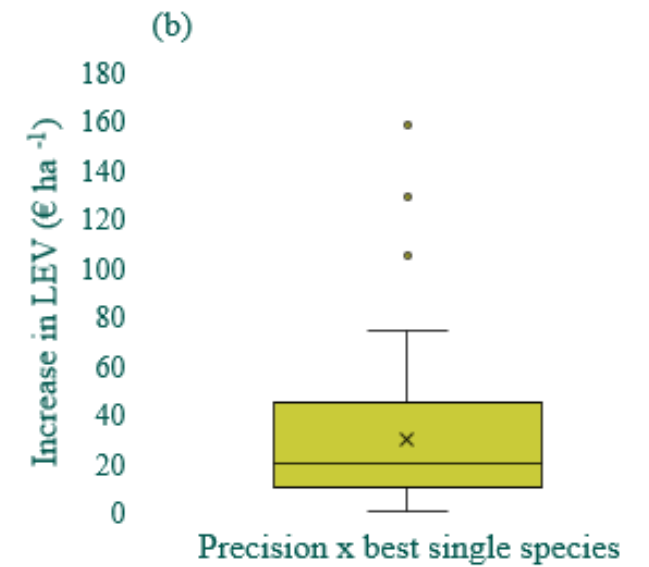
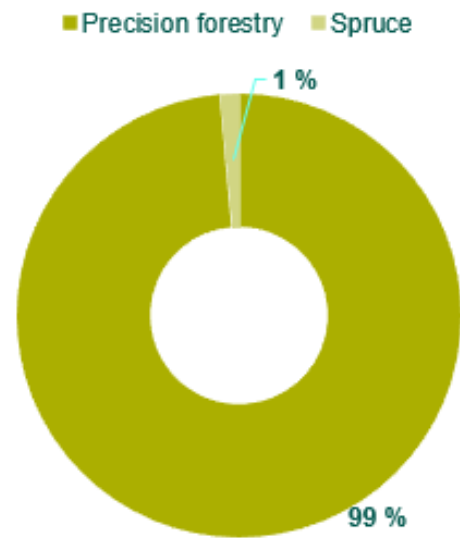
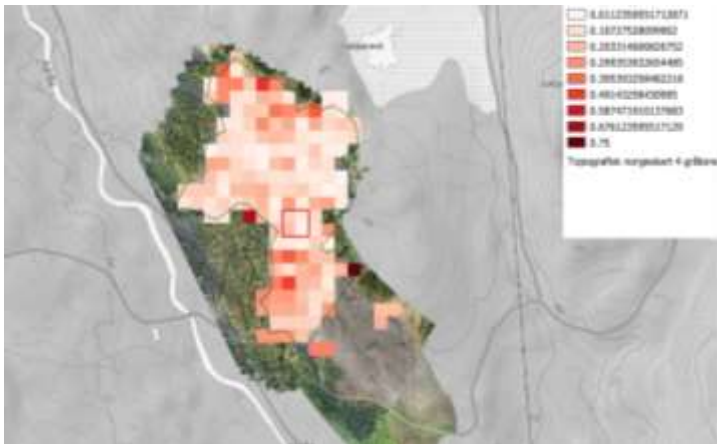
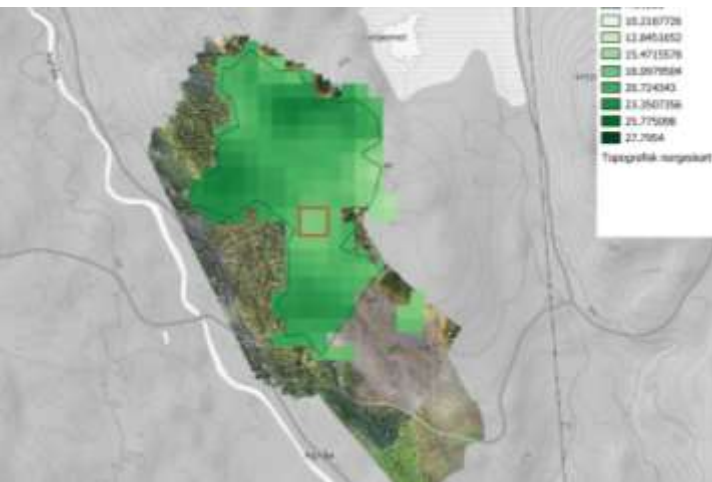


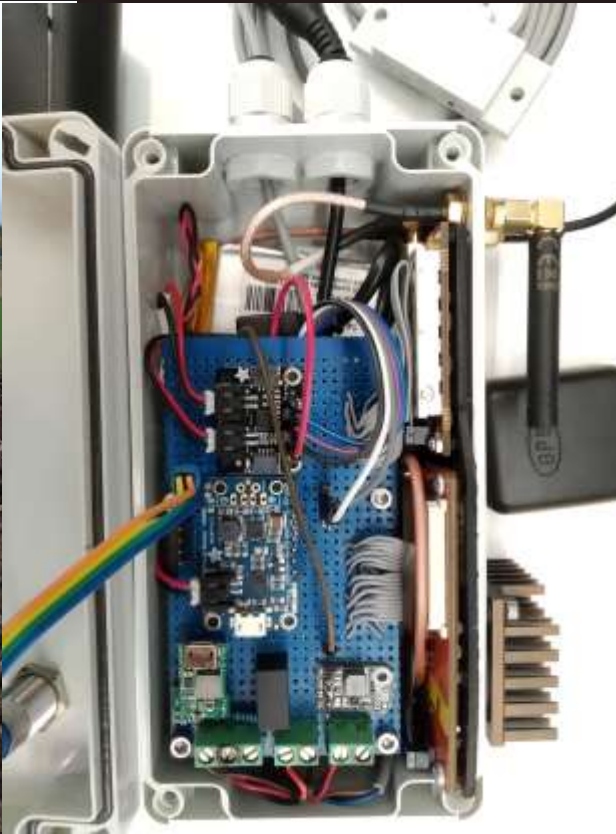
# Rotstand





# Precision forestry versus BAU







# Seedling positioning







SMART Forest



Forest inventory

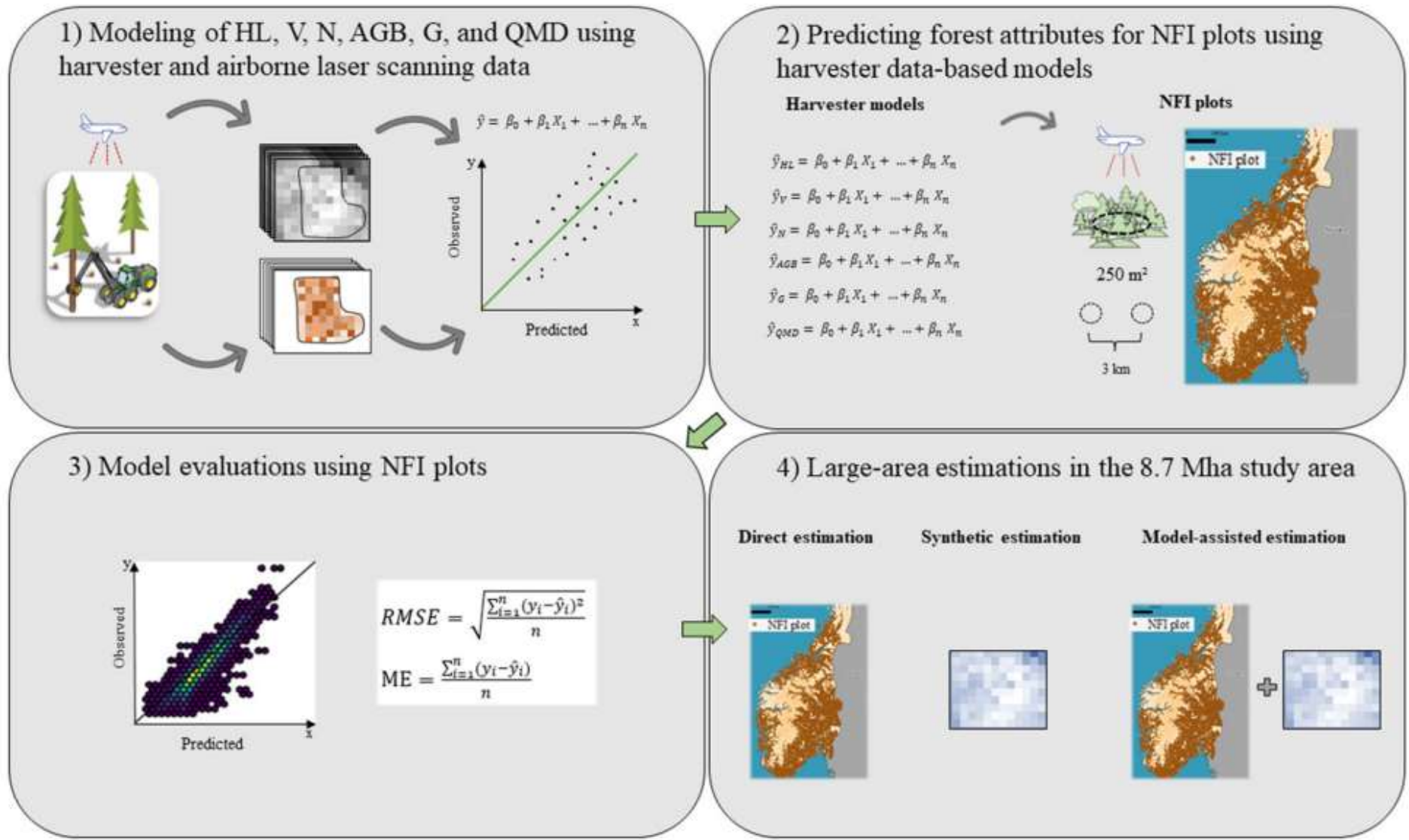
Silviculture

Harvesting

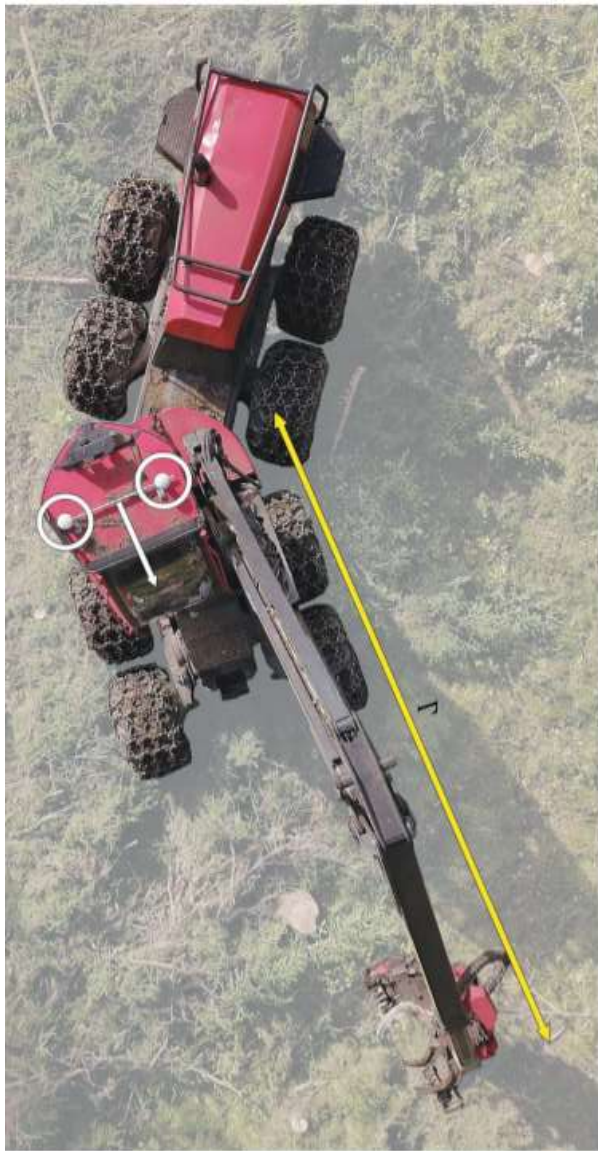
Wood supply









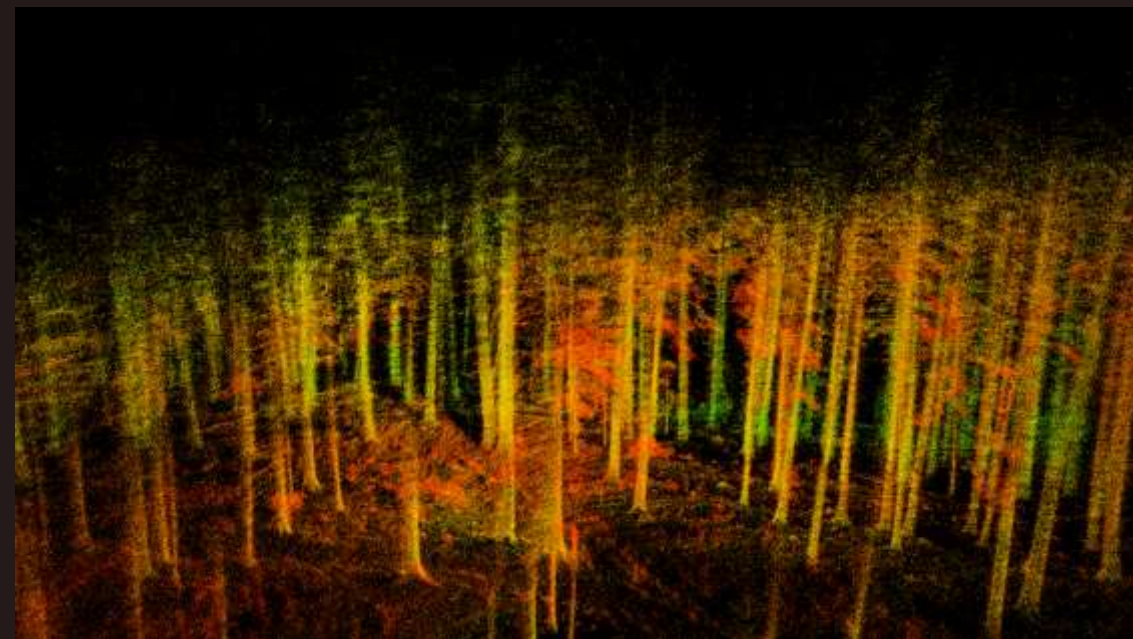
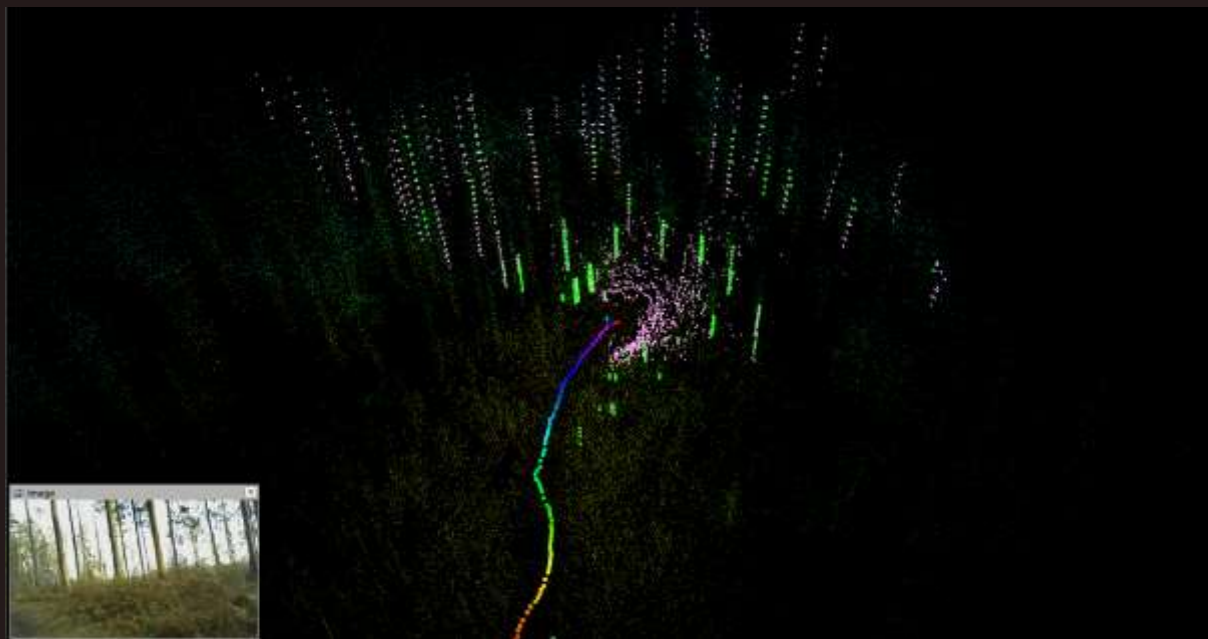


Noordermer et al. 2021. IJFE.



Horvat et al. (in prep)

# Mapping





# HarvestSens: Harvester head tracking and positioning





Forest inventory

Silviculture

Harvesting

Wood supply





NEXTBUSE NBDVR622GW

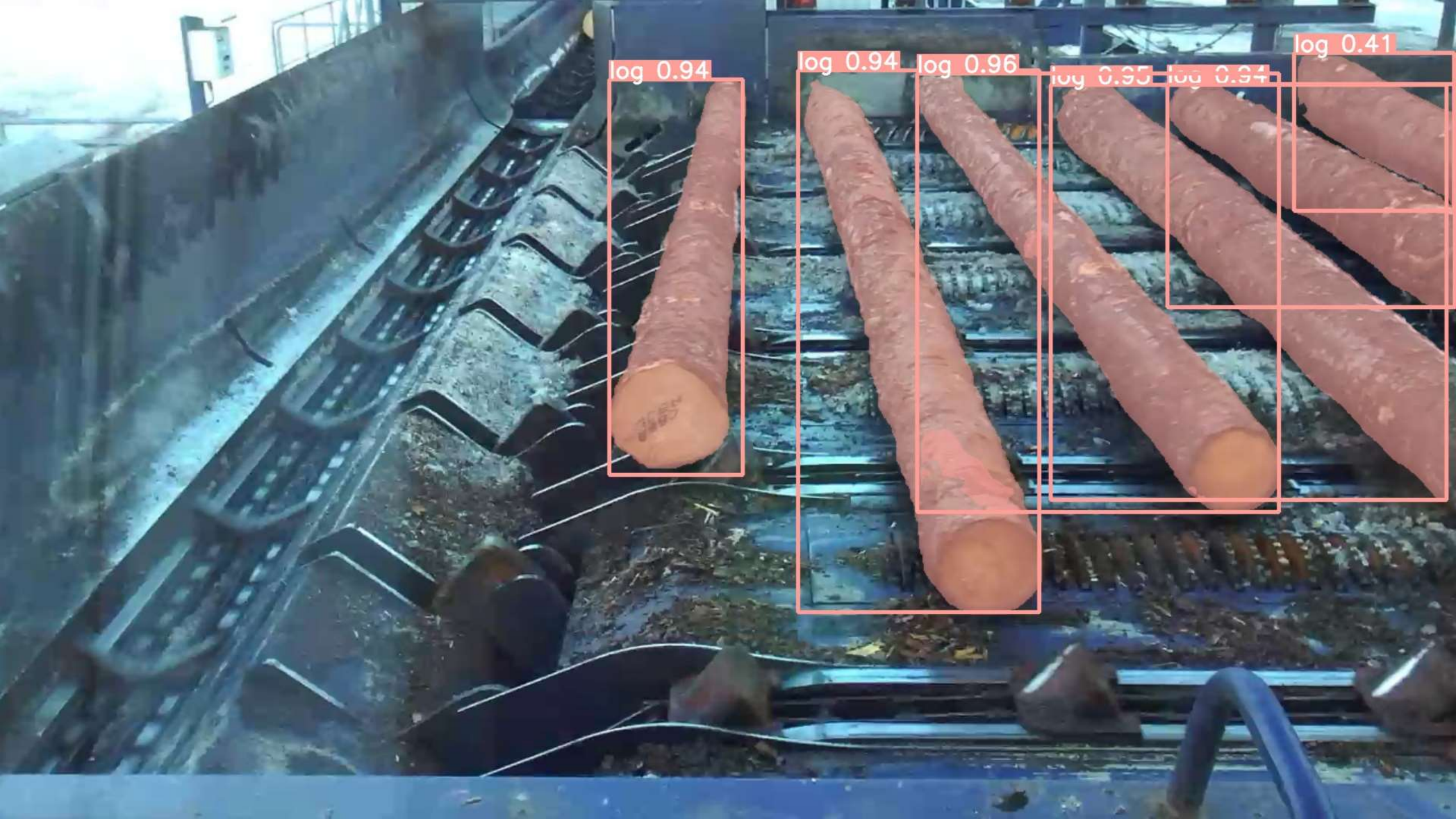
10:40:14 25/05/2022

SMART Forest









log 0.94

log 0.94

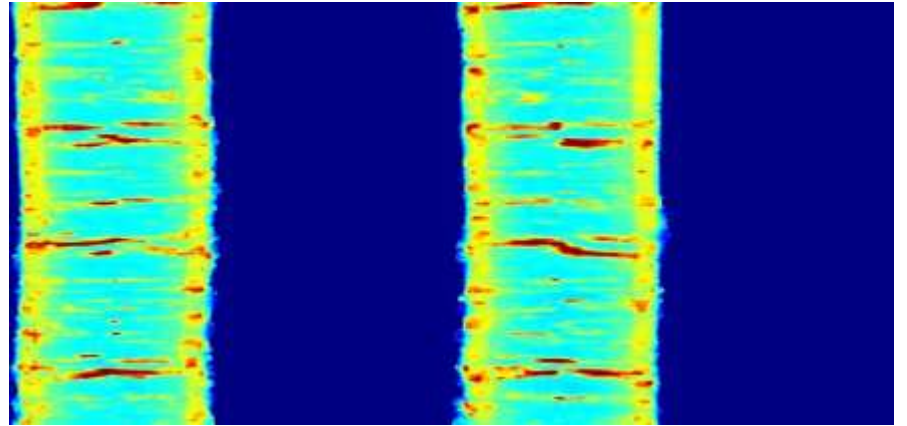
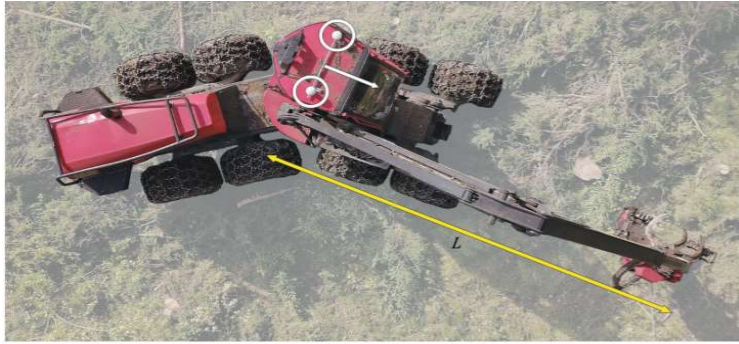
log 0.96

log 0.95

log 0.94

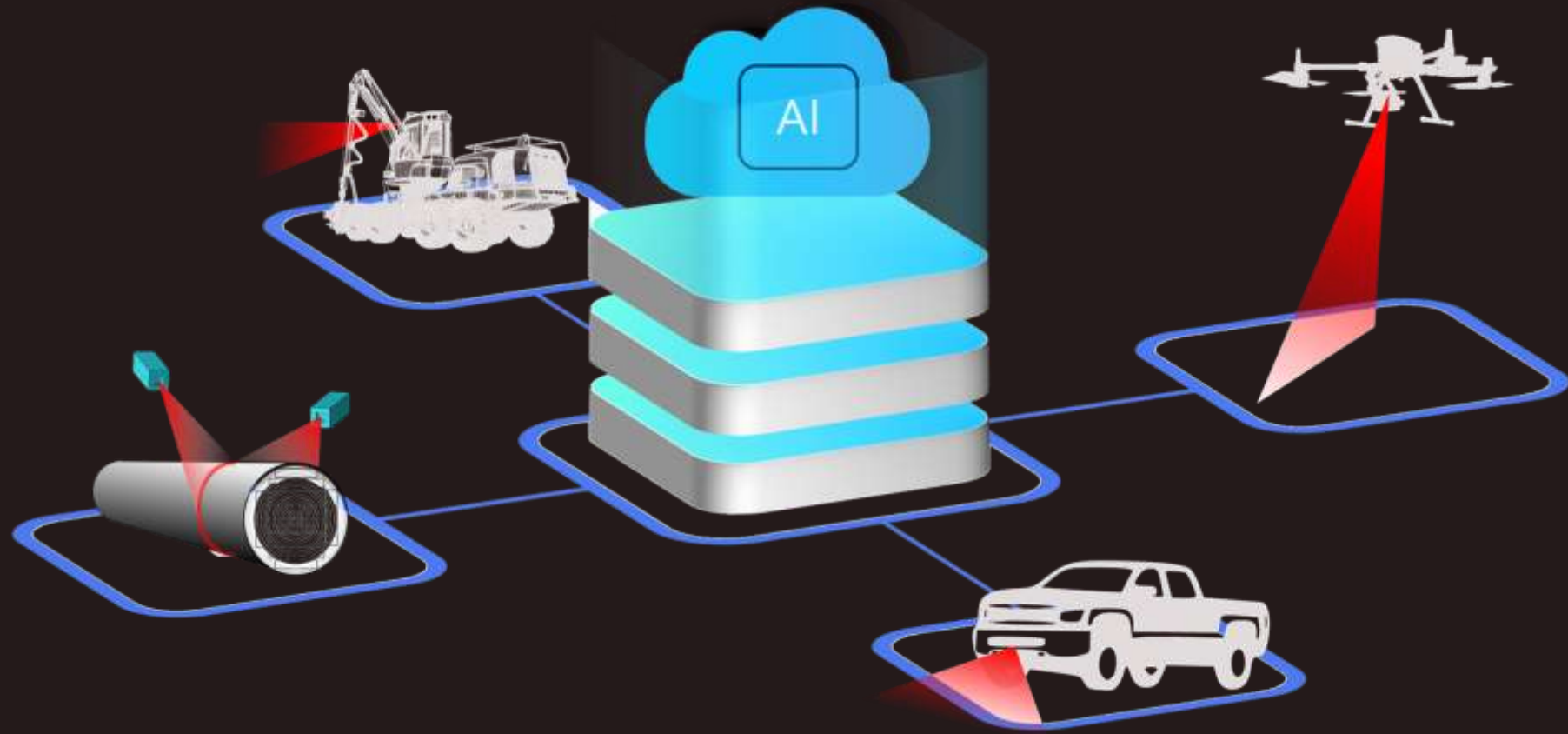
log 0.41





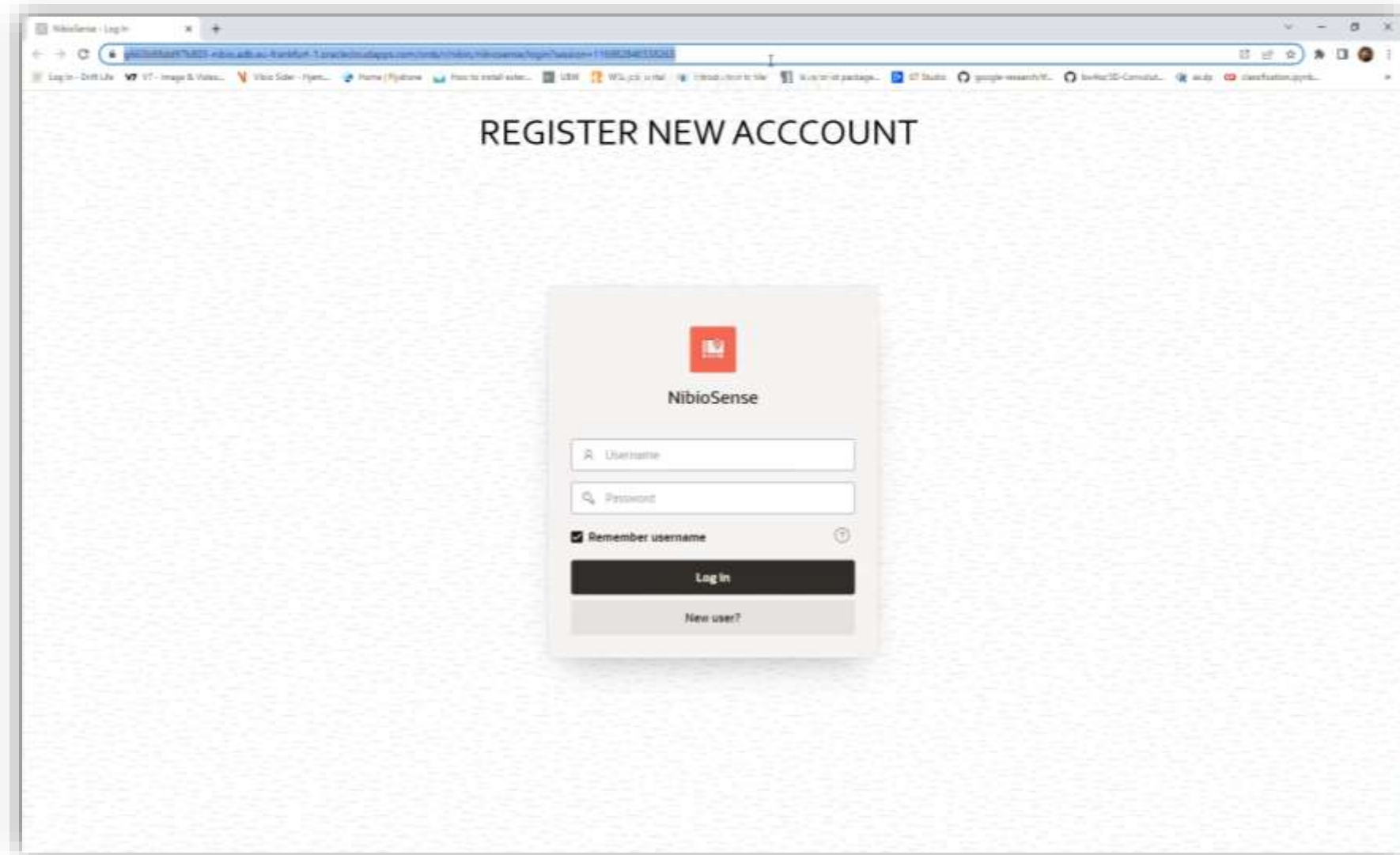


# ForestSens



Powered by









[www.smartforest.no](http://www.smartforest.no)

SMART Forest